hy-gain

308 Industrial Park Rd.
Starkville, MS. 39759

RC1-Y Controller

For Yaesu DC Rotators

INSTRUCTION MANUAL

RC1-Y FEATURES

- Direct replacement control box for Yaesu DC rotators: G-800. G-1000, G-2800
- Requires 13-14 VDC from station power supply.
- Computer control via either the USB port or RS-232 serial port.
- Graphic LCD screen with LARGE bright numbers and letters.
- Automatic speed up and slow down control.
- GOTO and Reciprocal heading button and knob for quick heading control
- Field upgradeable firmware via the USB port or serial port
- Rugged aluminum enclosure
- Made in U.S.A. in Starkville, MS.

QUICK USE GUIDE

For the RC1-Y model, it is as simple as connecting your 12-14 volt DC station power supply. You will need a 2.1mm plug and some 22-20 ga stranded wire. Wire the plug so the center conductor of the plug is **POSITIVE**. Unplug your Yaesu rotator from the old control box, and plug it into the new RC1-Y control box.

2.1mm
Positive
Negative
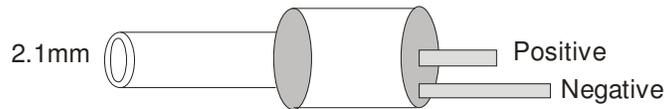
NOTE: Do not try using wire smaller than 22 ga as it will not handle the current.

For those who have older G-800/1000S or SDX models, they use a North stop system. Follow the instructions in the Menu section to invoke the North stop.

Warning: If you do not connect the old control box pin 1 (ground) to the ground (outside barrel of the power plug) you can get a ground loop and damage your power supply or send 24 VAC into your USB interface and computer. Ensure your power supply ground is also the RC1-Y ground.

Now that you have the rotor cables connected, and power to the box, you will see the graphic display come up with large center digits showing the current antenna position. To the lower right of the screen, you will see the current setting of the 'GOTO' control knob. Turn the GOTO knob and watch those digits change. To the lower left, you will see the 'CMD' heading. The CMD heading is the computer control heading. This can be either a command sent via the RS-232 port on the rear, or by pressing the GOTO button on the front panel. When you press the GOTO button, it transfers the GOTO heading into the CMD heading and starts turning your rotator. If you press and hold the goto button for several seconds, it will send a reciprocal (long path) heading of the knob's heading. Remember, it does the reciprocal of the GOTO knob's setting NOT the current position!

In the upper right, you will see one of 8 cardinal directions, which shows you which direction you are closest to: N, NE, E, SE, S, SW, W, and NW.

If you see the error message 'CABLE' on the screen, it means the RC1-Y box cannot see your rotor's position pot. Normally, you forgot to plug in the rotator cable, made a mistake in wiring your rotor plug, or your rotator pot is defective.

NOTE: The heart of this control is the rotator's position pot. If it is defective, the RC1-Y has no way of determining what to do. Although the left and right buttons will still move the rotor, no automatic features can be used. If your rotator is older, and your pot is noisy and intermittent, the RC1-Y will not be able to work correctly.

On models with overlap, like the Yaesu series, you will see the message on the right-hand side that says 'OVER' when you are in the overlap area. The Yaesu's will turn 450 degrees.

Once you have verified the control box is working by manually moving or using the GOTO feature and you see the center digits change normally, you are ready for computer control. Hook up a serial cable to the back of the RC1-Y box. A normal, 9-pin straight through (non-null) cable, is required. Turn on the control box. Bring up any number of rotor control programs like LP_Rotor or use the rotor control feature in Ham Radio Deluxe. Follow the instructions with that program, and set up the proper com port and the RC1-Y uses the DCU-1 protocol. There should not be a baud rate option, for all DCU1 uses 4800 baud N, 8, 1 (no parity, 8 data bits, 1 stop bit).

DXView is another program that does automatic rotator control. Some of these programs require you to tap the cursor on a simulated rotator face, and some a world map. There are also some that can be set to automatically turn the rotator to the station appearing in a DX cluster!

We have verified that the RC1-Y works well with any of the three programs mentioned above. A note about HRD version 5: this program will move the antenna but not provide azimuth feedback. HRD version 6 has been fixed.

Please see the Menu and Customizing section for Advanced Features of the RC1-Y, but, for now, it is pretty simple and powerful to use.

POSITION ACCURACY

The RC1-Y will normally end up within +/- 5 degrees of the desired heading when using computer control or the Goto button. This depends a lot on the wind load, and size of your antenna array. If your ending azimuth is always exceeding your desired heading, you may wish to use the COAST feature to turn off the motor a little early.

Most 3 or 4 element antennas have a large beam width of 50 degrees or more. With these antennas, being within half the beam width is plenty good enough accuracy. The RC1-Y's designer had 68 elements on UHF, and even with this array, 5 degrees was good enough!

Menus and Customizing

There are several menus available to customize your RC1-Y control box. The menu options are: Calibrate, Offset, Callsign, Defaults, Coast, Sleep, Northstop, Contrast, and Brake (if equipped).

To enter the menu system, press and hold the black encoder knob for several seconds and the MENU will come up. Turn the encoder shaft to change the entry value, and push the knob again to select the desired menu item.

Calibrate

Although you can calibrate the rotator for optimum accuracy, you may find that it is quite accurate without calibrating. We have found the pots in all rotors tested to be quite accurate. Most of the time, what you might require is the Offset feature, because your rotor is off the same amount of degrees all the time. That problem is corrected with Offset, not Calibrate.

If you desire to recalibrate your rotator, the RC1-Y does this by the start and end of the potentiometer, or LEFT stop or RIGHT stop. The RIGHT stop is 270 degrees in overlap for Yaesu models.

To calibrate the controller you can start by turning the rotator to either the RIGHT or LEFT end stop. Then go into the menu and select either the RIGHT or LEFT end stop calibrate function to calibrate the appropriate end stop. This must be the end stop where you have the rotator sitting at the time of calibration. The RIGHT end stop will calibrate to 270 degrees and the LEFT end stop will calibrate to 180 degrees.

Else, you must position the rotor to the left stop and right stop, and do NOT concern yourself with the antenna position right now. If the azimuth heading is not correct, you can use OFFSET to correct the azimuth. If your pot is off by a lot, for some reason, the RC1-Y will NOT accept the reading. Move the antenna first to the left stop until you see the antenna will no longer turn left. Do not use the display azimuth to determine if the antenna is as far left as it will go. Do a left stop calibrate. Similarly, move the rotor to the right stop and calibrate there. Now you can invoke some OFFSET to correct the azimuth on the display. Word of caution: it is possible that with a large offset required, that the hard stops of the rotor come into play. You may feel that the rotor 'turns the wrong way' on an automatic move. But that is possible with a large amount of offset put in.

Callsign

You may enter your callsign to customize YOUR RC1-Y controller. Select Callsign with the encoder knob. Then execute the callsign menu by pushing the encoder knob. Now rotate the goto knob and watch the first letter of your call appear on the lower screen. When that letter is correct, push the knob to move on to the next character or number. When finished push the knob with NO rotation.

Northstop

If you have an older Yaesu rotor where the mechanical stop is at North instead of South, you need this function. First, calibrate the rotor. Then select this menu and then hit the encoder knob to say Yes to North stop.

Offset

Most the time, this is the one thing most of us need to change. You might find the RC1-Y shows, for example, 120 degrees. If you go out and look and your antenna, and with a compass it is actually pointing 108 degrees. Well, then you need 108-120 offset of – 12 degrees. Zero degrees using the goto control, means zero offset. 010 goto control means +10 degrees. But, in the above example we need minus, and you can get minus degree by a reading to the left of zero degrees. In other words 350 is 10 degrees left of north (360 or zero degrees). So to get minus 12 we set the goto knob for 360-12 or 348 degrees. Then push the encoder knob. Pulse input rotors do not need overlap.

A few notes about offset…when setting an offset, do not forget about your hard stops (i.e. 181 degrees for the Ham series (left) and 180 degrees for the Yaesu (left)). So, you have 'offset' your display, let us say, 20 degrees plus. Well, the stop will now show up 20 degrees further at 201. Also, the rotor may seem to make wrong choices as to direction of turn, but it knows where the hard stops are, and will get you there. So, remember that using offset also 'offsets' your rotor stops and overlap areas as well.

Defaults

If you seriously mess up something in the menu system, you can undo all your mistakes by selecting the defaults menu and hitting the left button. This will wipe out any calibration, offset, and callsign you might have entered. The RC1-Y will restart after Defaults are invoked.

Contrast Level

The RC1-Y now has the ability to adjust the angle of view via an electronic contrast level. When you adjust the level with the encoder knob, the display adjusts instantly, showing you what you will get with the new setting. Press the encoder knob when you are satisfied with the display when done.

Sleep Timer

The RC1-Y has a default sleep timer of 10 minutes. At this time, with no button or RS-232 activity, the RC1-Y will go into a low power mode, clear the screen and shut off the lcd back light. Setting a time delay value of zero will disable the sleep mode. The numeric values are in minutes, up to 255 minutes. NOTE: some PC programs continuously poll the USB port. In these cases, the unit will never go to sleep. Shut down the PC program to disable the polling.

Brake Delay Timer

The RC1-Y has a default brake delay timer of 1.0 seconds. After the motor is stopped, the RC1-Y will time 'brake delay number of seconds' then turn off the brake solenoid, engaging the brake. This only applies to units with a brake. You may adjust the brake delay up to 5.0 seconds. If you also use the Coast feature, make sure your brake delay is long enough to allow your antenna to coast to that heading.

Coast Setting

The RC1-Y has the ability to add an antenna Coast setting. This setting is in degrees (up to 10) that will disengage the motor a few degrees early to allow your heading to be a little more accurate when the antenna comes to a stop. Be mindful that when you are coming up against the rotors hard, mechanical stops, that this feature will not help. Also, when automatic GOTO or computer settings are invoked, changes less than 20 degrees will not use the coast setting.

Reverse LCD

The RC1-Y has the ability to reverse the pixels on the LCD screen. The normal or default look is white numbers on a blue background. By setting Reverse, you may see blue numbers on a white background, which could aid in viewing the screen if your vision is impaired.

Flash upgrade

The RC1-Y is capable of field program upgrade via its Serial port input. You may have noticed that the RC1-Y seems to have a slight delay during power up. It is during this time that the built-in bootloader program is active, looking for the proper command sequence to begin a flash upgrade of the internal program memory.

Upgrade Procedure

On the RC1-Y control box set the POWER switch to the OFF position. Make sure the serial cable is plugged into the RC1-Y and your computer. Start the TeraTerm program included on the CD. Select Serial and your virtual com port number on the opening screen (You may have to go to Device Manager/Com Ports to see what com port number it is). Click the Setup tab. Select Serial Port. Make sure the proper com port is set, then set 9600 baud N81 (no parity, 8 bits, 1 stopbit) and none for flow control, and 50 into msec/line delay box. Select Setup/Terminal and change the Transmit from CR to CR + LF. You cannot use the usb port to upgrade the unit!

Now find your downloaded upgrade hex file from MDS. In TeraTermPro select File, then Send File, and highlight the upgrade hex file, BUT do not click the OK button yet!! Within 4 seconds elapsed time, power up the RC1-Y box and click OK on TeraTerm file send window. This must be done within the 4 second window.

You will see TeraTerm send the data, the RC1-Y will return xxK message to show each 1K of memory written and then give a SUCCESS message in its terminal window.

If the RC1-Y just powers up normally, you did not make the upgrade power up within the 4 second window. If you see an error message in the TeraTerm terminal window, you probably did not set the msec/line delay that is necessary. If you see random characters in the terminal window, you probably did not set the baud rate to 9600 baud N81 with no flow control.

If all else fails and you feel uncomfortable with this upgrade procedure, you may send your unit back for upgrade at no charge except you must pay shipping both ways.

If you power the RC1-Y without upgrade, you will see a BOOT message, then a TIMEOUT message, telling you it has made it to the boot loader, and then it did NOT receive the proper hex file header, and quit because the 4 second limit happened.

DCU-1 Protocol

The DCU1 protocol is one of the most popular control protocols for antenna rotators. It allows the control and monitoring of your rotator via packets of commands send to your computer's serial port. Normally, these commands are part of a separate program like LP_Rotor, but also can be built into more complex programs like Ham Radio Deluxe, or DXView.

There are three command frames and one character command:
"AM1;" which means start turning
"AP1xxx" which means the new heading is xxx
"AI1;" which means send me your current position
";" which means stop the rotor

NOTE: Some programs do not use the full DCU1 protocol. There are some programs which expect the rotor to turn by ONLY sending the AP1xxx command. The RC1-Y needs both the AP1 and the AM1 commands to begin movement.

Error Messages

There are two error messages shown on the screen: CABLE, and MOTOR.

CABLE

If this message appears on the display it means that the cpu chip is unable to read the pot inside your rotor. For older rotors, this means the pot is dirty or corroded and intermittent. You can verify this moving the rotor with the left or right button and see if the message goes away and the main position digits start moving again.

Another cause of the message CABLE could be a bad connection either at the rotor or control box end. Your pot is most likely 500 ohms maximum, down to near zero ohms. This is determined by measuring the resistance between pins 2 and 3.

MOTOR
If this message appears on the display, it means that the cpu has not detected enough movement of your rotator motor in a specific amount of time. This could be caused by high winds or a cable has caught, or the mast is slipping in the rotor mast clamp. Alternatively, this message could also indicate an open circuit in the motor wiring. For the Yaesu this is pins 4 and 5. For the Ham series you have the complication of several factors: motor, brake, and motor capacitor.

LEFT STOP and RIGHT STOP messages (Version 1.4 and above) tell you that you have hit the left or right mechanical stops in your rotor.

Theory of Operation
Your RC1-Y control box uses some of the latest in microcontroller technology. A microcontroller differs from a microprocessor in that microcontroller has everything it needs built into it, like program memory, ram, analog-to-digital converters, timers, eeprom to store permanent values, input/output ports, and many other features. We use a PIC 18F45K50 processor with built-in USB. This allows us to do serial or USB operations. However, only one or the other can be used. You cannot use both RS-232 or USB at the same time.

The analog-to-digital converter reads the pot on your rotor 10 times per second. Then it uses a process called digital signal processing (DSP) to noise filter, and average those readings to produce to the firmware a smooth reading. But still, with an unusually dirty pot, no amount of filtering will help. If your pot goes from, say, 200 ohms to infinity (open), the dsp cannot recover from dozens of infinity readings, but CAN recover from a few bad readings easily. The pot reading is the heart of the RC1-Y control. We must have feedback from the rotor to control it properly.

Power relays controlled by output lines from the PIC 18F45K50 control your rotor motor. In the case of d.c. rotor motors like the Yaesu there is a power relay and a direction relay.

Control is more complicated for the Yaesu and d.c. rotor motors. The RC1-Y has built-in circuitry for producing the 12 to 28 volts d.c. the motor requires. When the turning requirement is small, under 30 degrees, the RC1-Y will produce low voltage (12) only. When more than 30 degrees, the voltage ramps up quickly from 12 to 28, then, when approaching the target heading, slows down again by ramping down the voltage.

One of the more complicated tasks the RC1-Y has to do is to show you, the user, what is happening, on the LCD screen. This is a bit-mapped graphic screen of 128 by 64 pixels with white led backlight. All the characters on the LCD are formed by writing streams of pixels, not characters, to the screen.

hy-gain® LIMITED WARRANTY

hy-gain Warrants to the original owner of this product, if manufactured by *hy-gain* and purchased from an authorized dealer or directly from *hy-gain* to be free from defects in material and workmanship for a period of **12** months for rotator products and **24** months for antenna products from date of purchase provided the following terms of this warranty are satisfied.

1. The purchaser must retain the dated proof-of-purchase (bill of sale, canceled check, credit card or money order receipt, etc.) describing the product to establish the validity of the warranty claim and submit the original or machine reproduction of such proof-of-purchase to *hy-gain* at the time of warranty service. *hy-gain* shall have the discretion to deny warranty without dated proof-of-purchase. Any evidence of alteration, erasure, or forgery shall be cause to void any and all warranty terms immediately.

2. *hy-gain* agrees to repair or replace at *hy-gain's* option without charge to the original owner any defective product under warranty, provided the product is returned postage prepaid to *hy-gain.*

3. Under no circumstances is *hy-gain* liable for consequential damages to person or property by the use of any *hy-gain* products.

4. Out-of-warranty Service: *hy-gain* will repair any out-of-warranty product provided the unit is shipped prepaid. All repaired units will be shipped COD to the owner. Repair charges will be added to the COD fee unless other arrangements are made.

5. This warranty is given in lieu of any other warranty expressed or implied.

6. *hy-gain* reserves the right to make changes or improvements in design or manufacture without incurring any obligation to install such changes upon any of the products previously manufactured.

7. All *hy-gain* products to be serviced in-warranty or out-of-warranty should be addressed to *hy-gain*, **308 Industrial Park Road, Starkville, Mississippi 39759, USA** and must be accompanied by a letter describing the problem in detail along with a copy of your dated proof-of-purchase.

8. This warranty gives you specific rights, and you may also have other rights which vary from state to state.